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WeMor	51.1 Legiged and Mumanoid Robots (LEG-1)	1. ICC 405 - RAKENOC: Reachability-Assers K. Order Markov Path Optimization. 2. ICC 465 - Learning Path Recovery Strategies for Humanoid Rabobol Using DRU. 3. ICC 665 - Learning Termi-Socialized Policies for Adaptive Locerosion.	We Mor	52. 1 Rehabilitation Robotics (MED-1)	2. ID: 483 - Consign of an Arti-lock Mechanism for Namronic Drive Guarteg. 2. ID: 485 - A Comparative Study of Interaction Force Estimation Methods for Transparency Control. 3. ID: 416 - Sharenstic Evaluation of a Series Estatic Actuator-Fowered Prosthetic Knee Joint 1. ID: 416 - Sharenstic Evaluation of a Series Estatic Actuator-Fowered Prosthetic Knee Joint 1. ID: 416 - Sharenstic Evaluation of a Series Estatic Actuator-Fowered Prosthetic Knee Joint 1. ID: 416 - Sharenstic Evaluation of a Series Estatic Actuator-Fowered Prosthetic Knee Joint 1. ID: 416 - Sharenstic Evaluation of a Series Estatic Actuator-Fowered Prosthetic Knee Joint 1. ID: 416 - Sharenstic Evaluation of Actuation Sharenstin Sharen	We Mor	53.1	Control, Dynamics and Manipulation (CTRL-1)	1. ID: 417 - Development and Genetic Algorithm Optimization of a Constaint-tonque Robotic Gripper 2. ID: 655 - Development of Metrics based on the Impediance Space bit Hybrid Impedance Controllers 3. ID: 695 - Development of Metrics based on the Impediance Space bit Hybrid Impedance Controllers 3. ID: 695 - Development of Metrics bits of the Metrics Stating Mode Controller				
We Eve	51.2 Legged and Humanoid Robots (LEG-2)	4. ID: #G3 - Meta Reinforcement Learning Applied to Quadrupedal Rebots for Blind Locomotion 2. ID: #73 - Dopanies Medicalized Spiking Cintral Pattern Generators for Gall Selection 6. ID: #14 - Loca-Stead Visitor Tearningies Medicalized for Reformation Selections 6. ID: #14 - Loca-Stead Visitor Tearningies Medicalized for Redots Resolutions	We Dee	52. 2 Rehabilitation Robotics (MED-2)	4. D: #100 - Comparison of Adaptive Control Strategies for a Unitativa Executable Executables 5. D: #20 - Impedance Control With Neural Network Estimation of the Natural Exceptables Interaction Torques 6. D: #213 - Impedance Control With Neural Network Estimation Services 6. D: #213 - Impedance Control Terrecord to Perform Executables Interaction 7. Description Control Services Control Control Control Control Control Control Control 7. Description Interaction 7. Description Control 7. Description Control 7. Description Control 7. Description 7.	We Eve	53.2	Control, Dynamics and Manipulation (CTRL-2)	4. ID: #52 - Efficient Dynamic Modeling for 3D Deformable Object Manipulation 5. ID: #60 - AffordGen: Affordance-Based Distant Generation for Robot Manipulation Learning 6. ID: #107 - Generative Dynamic Canadable Area Enteriors with Originary Canadabats 6. ID: #107 - Generative Dynamic Canadabat Area Enteriors with Originary Canadabats 6. ID: #107 - Generative Dynamic Canadabat Area Enteriors with Originary Canadabats 6. ID: #107 - Generative Dynamic Canadabat Area Enteriors with Originary Canadabats 6. ID: #107 - Generative Dynamic Canadabat Area Enteriors 6. ID: #107 - Generative Dyn				
We Eve	51.3 Path Planning and Navigation (NAV-1)	1. 10: 92.49 - Casto-Casto Various irrathermation intercentains for induced, applications 1. 10: 92.29 - Laboration window irrathermation intercentains for induced, applications 1. 10: 92.2 - Nettion Planning and Control of an Overacturated 4-Whites Drine. 1. 10: 92.2 - Nettion Planning and Control of an Overacturated 4-Whites Drine. 1. 10: 92.21 - Nettion Planning and Control of an Overacturated 4-Whites Drine. 1. 10: 92.21 - Nettion Planning and Control of an Overacturated 4-Whites Drine. 1. 10: 92.21 - Netions Planning and Control of an Overacturated 4-Whites Drine.	We Eve	52.3 Multi-Robot Systems (MRS-1)	0. VE 1223 - Hingyratio Updates and Lorentz-Internetions for Francisco Statistics 1. W. 677 - Children Children Children Statistics 1. W. 677 - Children Children Children Statistics 1. W. 677 - Children Children Children Children Statistics 1. W. 677 - Children Children Children Children Children Children Children Children 1. W. 670 - Children Children Children Children Children 1. W. 670 - Children 1. W. 67	We Eve	53.3	Simulation and Learning (SIM-1)	10: 187 - George Contrary Contract Companies Annie Energies August Contract Con				
We Eve	51. 4 Path Planning and Navigation (NAY-2)	4. ID: 451 - Semantics-Arean Path Planning for Quadrupedal Robots	We Eve	52. 4 Multi-Robot Systems (MRS-2)	Lib. 442 - Elastic Fermation Centres for Robot Saverna Using Opramic Soundary-Sased. S. Dr. 1932 - Multiple Line Coordination Approach in Robotic Saverna to Navigate Through Narrow. Dr. 1935 - Oncompative Analysis of Tradector Generation Societies for Multiple Robotic Robo	We Eve	52.4	Simulation and Learning (SIM-2)	A. ID. #152 - Adiabatic Painforcement Learning S. ID. #152 - Adiabatic Painforcement Learning S. ID. #155 - 0-OOF Modeling and Simulation of a Collaborative Catamana Unmanned Wehicle. S. ID. #13 - 5-OOF Modeling and Simulation of Conference of University of Rebotics S. ID. #13 - 5-OOF Modeling Annual Community of Conference of Conference of Conference on Co				
We Eve	51.5 Biologically-Inspired Robot (BIO-1)	1. ID: #72 - Development of an Autonomous Hexapod Robot for Ant Teal Following 2. ID: #837 - Embodied Inhaligence for Advanced Bioinspired Microsobotics: Exemples and Insights 3. ID: #877 - Development Validation of Bio-Insight Modular Prohibition City to Lunar	We Eve	52.5 Human Robot Interaction (HR-1)	1. ID: 4174 - Multimodal Attention Contaction in Child-Bobot Storyfelling A Machine Learning Frammersk 2. ID: 827 - MilhillaGe: A Machine Reality Interface in Milk of class-Chierted Control 3. ID: 414 - Realizading Lateration Little Massed Milkinst Learning Commands for the Robot Navigation	We Eve	53.5	Unmanned Aerial Vehicles (UAV-1)	I. ID: #12 - Parrot Analt: Model Identification for Outdoor Control Applications Z. ID: #84 - A Companitor Study of Chone Dynamic Controllers Based on Linear NPC X. ID: #185 - Linear Planning Linyarin Controllers or a Reliable Outdricer				
Thu Mor	51.6 Path Planning and Navigation (NAV-3)	1. 10: 430 - Costant-Assure Model-Based Reinforcement Learning for Autonomous Racing 2. 10: 4120 - Safe Path Following for a Differential Drive Robet using Vector Fast Guidance 3. 10: 4130 - Safe Path Following for a Differential Drive Robet using Vector Fast Guidance 3. 10: 4133 - Safe Pathwise Sasand referense investment and surfavour environment	Thu Mor	52.6 Rehabilitation Rebotics (MED-3)	7. ID: M6 - Designing a Multimodal Sa Colf Lower-Limb Enackelation for Overground 8. ID: 977 - Preliminary Evaluation of Virtual Resids Colven Hundre Markine Training 9. ID: M63 - Development of a Low Colf Reduct Elbow Sensitives for Land Hundre Markine Sensitives	Thu Mor	53.6	Control, Dynamics and Manipulation (CTRL-3)	1.10: K28 - Task-Critical Part Alignment Improves Imitation of Object Interactions 2.10: M1 - Sumple-4 Risem Motion Generalization via Task-Parameterized CMMs. 3.10: K97 - Semple-4 Risem Motion Generalization via Task-Parameterized CMMs. 3.10: K97 - Semple Taskpoth Syndromy Generation for Robect in Regulation Units Adaptive Task-Based 5-Curve				
Thu Mor	51.7 Path Planning and Navigation (NAY-4)	4. ID: #242 - Duslasting Coverage Path Planning Strategies for UNI's with Real-Time Obstacle Avoidance 5. ID: #173 - Adaptive Copishap-based Path Planning in Partially Rosen Environments. 6. ID: #1847 - Accessariative Social Collection For Commission Commission for an Obstacle Commission Collection Food Collection	Thu Mor	52.7 Rehabilitation Robotics (MED-4)	Do. Di. 115 - Robelic Cana Control via Admittance, Dynamic and Impediance Post-Surgical Uner Cana Study Di. 105 - 973 - Politimizary Investigation of Virtual Reality versus Non-Virtual Reality. Di. 105 - 974 - Politimizary Investigation of Virtual Reality versus Non-Virtual Reality. Di. 105 - 975 - Politimizary Investigation of Virtual Reality versus Non-Virtual Reality. Di. 105 - 975 - Politimizary Investigation of Virtual Reality versus Non-Virtual Reality. Di. 105 - 975 - Politimizary Investigation of Virtual Reality versus Non-Virtual Reality. Di. 105 - 975 - Politimizary Investigation of Virtual Reality versus Non-Virtual Reality. Di. 105 - 975 - Politimizary Investigation of Virtual Reality versus Non-Virtual Reality. Di. 105 - 975 - Politimizary Non-Virtual Reality versus Non-Virtual Reality. Di. 105 - 975 - Politimizary Non-Virtual Reality versus Non-Virtual Reality. Di. 105 - 975 - Politimizary Non-Virtual Reality versus Non-Virtual Reality. Di. 105 - 975 - Politimizary Non-Virtual Reality versus Non-Virtual Reality. Di. 105 - 975 -	Thu Mor	53.7	Control, Dynamics and Manipulation (CTRL-4)	d. ID: #225 - Stability and Performance Analysis of Presurvatic Levitation System. 5. ID: #1275 - Leveraging Pro-Hamiltonian Theory for Impedance Control Benchmarking D: ID: #1275 - Leveraging Pro-Hamiltonian Theory for Impedance Control Benchmarking D: ID: #1205 - Teleposeration of Anal Manibuston with Impatrix-Saward Hamiltonian Williams				
Thu Mor	51.8 Robotics Vision and Perception (WS-1)	1. IO: 403 - Official to-based RGB-O Semantic Segmentation with Deformable Attention 2. IO: 483 - Comparative Analysis of Transformer-Based Segmentation Nationals to Nationals Segmentation 3. IO: 599 - Comparative Analysis of Transformer-Based Segmentation Nationals Nationals Segmentation 3. IO: 599 - Semantic-Analysis Section from Miscolar Result Forum Recognition Section Section 1.	Thu Mor	52.8 Aquatic Robots (AQUA-1)	1. Dr. #55 - Navigating the Sim-to-Read Gay: A Chilcral Analysis of Underwater Robolics Simulations 2. Dr. #606 - AguaPartie - an Underwater Wisio Learning-Boase Chinacement Method. 3. Dr. #606 - Hearning Lot Goldsen Control in Palls Conformation With Dear Templace Componentation for a Differential UDY 1. Dr. #106 - Hearning Lot Goldsen Control in Palls Control in Palls Componentation for a Differential UDY	Thu Mor	53.0	Unmanned Aerial Vehicles (UAV-2)	4. ID: 84 - Leveraging Vocel-Based Structures (Point-LIG-Volo) for Efficient SLAN 5. ID: 4129 - Model Predictive Control with Seri Constraints for UNIV Trajectory Tracking 6. ID: 4141 - UNIPIEC Tracking To SC Design Astronomy Across Embodiments 10. ID: 4141 - UNIPIEC Tracking To SC Design Astronomy Across Embodiments 10. ID: 4141 - UNIPIEC Tracking To SC Design Astronomy Across Embodiments 10. ID: 4141 - UNIPIEC Tracking To SC Design Astronomy Across Embodiments 10. ID: 4141 - UNIPIEC TRACKING TO SC Design Astronomy Across Embodiments 10. ID: 4141 - UNIPIEC TRACKING TO SC Design Astronomy Across Embodiments 10. ID: 4141 - UNIPIEC TRACKING TO SC Design Astronomy Across Embodiments 10. ID: 4141 - UNIPIEC TRACKING TO SC Design Astronomy Across Embodiments 10. ID: 4141 - UNIPIEC TRACKING TO SC Design Astronomy Across Embodiments 10. ID: 4141 - UNIPIEC TRACKING TO SC Design Astronomy Across Embodiments 10. ID: 4141 - UNIPIEC TRACKING TO SC Design Astronomy Across Embodiments 10. ID: 4141 - UNIPIEC TRACKING TO SC Design Astronomy Across Embodiments 10. ID: 4141 - UNIPIEC TRACKING TO SC Design Astronomy Across Embodiments 10. ID: 4141 - UNIPIEC TRACKING TO SC Design Astronomy Across Embodiments 10. ID: 4141 - UNIVERSE TRACKING TO SC DESIgn Astronomy Across Tracking To Sc Design Astronomy Across Tracking Tr				
Thu Eve	51.9 Robotics Vision and Perception (VIS-2)	4. ID: 4126 - A Comparative Analysis of Class Imbalance-Aware Loss Functions for Sensoric Segmentation 5. ID: 4148 - Insproved Plant-Time Segmentation of Structure and Times Uniting 2D-2D Vocal Analysis 6. ID: 4727 - Appearance Based Termic Lossellacides (help Ceep Learning for Autonomous Navigation) 6. ID: 4727 - Appearance Based Termic Lossellacides (help Ceep Learning for Autonomous Navigation)	Thu Eve	52.9 Aquatic Robots (AQUA-2)	4. ID: #136 - A Naigation Approach For Autonomous Salbout Based on Human Salbr Perception 5. ID: #278 - Model Predictive Contouring Control with Time-Optimal Trajectory Planning for Autonomous Surface Vehicles	Thu Eve	53.9	Unmanned Aerial Vehicles (UAV-3)	7. ID: #85 - Outdoor Drown Navigation: Evaluating Communication Limits of an Offboard Controller E. ID: #23 - Autonomous Mapping and Navigation Unit for Annia Robots S. ID: #357 - Nation Control Mapping and Navigation Unit for Annia Robots S. ID: #357 - Nation Your Control Annia Mittade Control Landon Robitational Statems The Control of the Control of the Control of the Control Control Control of the Contro				
Fri Mar	51.10 Legged and Humanoid Robots (LEG-3)	1. IO: 481 - Nonlinear Calturbance Observer Based Force Control for the Hydraulic Actuator of the Hyd Robot 2. IO: 4910 - Hearst-foot, Algebra-Based Control Architecture for Tolgectory Tracking, 3. IO: 4910 - Hazam-Robot Call Movement Maccanic aire of large Moving Call Call Call 3. IO: 4910 - Hazam-Robot Call Movement Maccanic aire of large Moving Los Ground	Fri Mar	52.10 Multi-Robot Systems (MRS-3)	7. ID: #546 - Deparative Central of Multiple Droses for Load Transportation. 8. ID: #527 - Multi-Robotic Coordinated Motion Finance Training Line-6-Sight Connectivity 9. ID: #517 - Formation Control of Histogeneous Modific Manipulation State of Linear Markets State of Control Contro	Pri Mor	53.10	Unmanned Aerial Vehicles (UAV-4)	10. ID: #183 - Scalable real-time mask-UAV coverage path planning for large geographical areas 11. ID: #23 - Wind further inspection: An autonomous UAV-based approach 12. ID: #20 - Plannetisted Brownine Model for PIH-P-Refl Quadreties				
Fri Mar	51.11 Robotics Vision and Perception (VIS-3)	7. ICI: 1506 - EPICS - Expert-based Point Cloud Segmentation of OR Road LEMA 8. ICI: 447 - Approximate Expervised Object Obstance Estatution on the manued Surface Vehicles 9. ICI: 447 - Farming to Recruitate Vehicles (Temporary for Deep Learning Estate Understand Source 9. ICI: 447 - Farming to Recruitate Vehicles (Temporary for Deep Learning Estate Understand Source 9. ICI: 447 - Farming to Recruitate Vehicles (Temporary for Deep Learning Estate Understand Source 10. ICI: 447 - Farming to Recruitate Vehicles (Temporary for Deep Learning Estate Understand Source 11. ICI: 447 - Farming to Recruitate Vehicles (Temporary for Deep Learning Estate Understand Source 12. ICI: 447 - Farming to Recruitate Vehicles (Temporary for Deep Learning Company) 13. ICI: 447 - Farming to Recruitate Vehicles (Temporary for Deep Learning Company) 14. ICI: 447 - Farming to Recruitate Vehicles (Temporary for Deep Learning Company) 15. ICI: 447 - Farming to Recruitate Vehicles (Temporary for Deep Learning Company) 16. ICI: 447 - Farming to Recruitate Vehicles (Temporary for Deep Learning Company) 17. ICI: 447 - Farming to Recruitate Vehicles (Temporary for Deep Learning Company) 18. ICI: 447 - Farming to Recruitate Vehicles (Temporary for Deep Learning Company) 18. ICI: 447 - Farming to Recruitate Vehicles (Temporary for Deep Learning Company) 18. ICI: 447 - Farming to Recruitate Vehicles (Temporary for Deep Learning Company) 18. ICI: 447 - Farming to Recruitate (Temporary for Deep Learning Company) 18. ICI: 447 - Farming to Recruitate (Temporary for Deep Learning Company) 18. ICI: 447 - Farming to Recruitate (Temporary for Deep Learning Company) 18. ICI: 447 - Farming to Recruitate (Temporary for Deep Learning Company) 18. ICI: 447 - Farming to Recruitate (Temporary for Deep Learning Company) 18. ICI: 447 - Farming to Recruitate (Temporary for Deep Learning Company) 18. ICI: 447 - Farming to Recruitate (Temporary for Deep Learning Company) 18. ICI: 447 - Farming to Recruitate (Temporary for Deep Learning Comp	Fri Mar	52.11 SLAM(SL-1)	1. ID: #55 - Change Detection and Model Update from Limited Query Data 2. ID: #65 - Investigation of Africa Marker Placement for Plans Indoor Localization 3. ID: #65 - Vesseligation of Africa Marker Placement for Plans Indoor Localization 3. ID: #65 - Vesseligation of Africa Marker Plans Indoor Localization 3. ID: #65 - Vesseligation of Africa Marker Plans Indoor Localization	Fri Mor	53.11	Industrial and Service Robotics (IND-1)	1. IC: 664 - An Autonomous Floor Clearing Strategy to Tidy up Unknown Home Environments 2. IC: 663 - Ethically-Aligned Safety Mentioning in CMC Machining via Certological Medicing 3. IC: 663 - Ethically-Aligned Safety Mentioning in CMC Machining via Certological Medicing 3. IC: 663 - Ethically-Aligned Safety Mentioning for PMC				
Fri Mar	51.12 Robotics Vision and Perception (VIS-4)	10. ID: #110 - Generation and Registration of Multi-Densain Point Clouds of Othbare Structures. 11. ID: #107 - Fersioner IPGA-Accelerated Value-Based Terans Cloudstation for Autonomous Robot Navigation 12. ID: #166 - This Place Locks Trailing: Value-Based Serians Chapting for Indians Commiss 12. ID: #166 - This Place Locks Trailing: Value-Based Seriansic Naping for Indians Commis	Fri Mar	52.12 SLAM(SL-2)	4. ID: 460 – Biolinspired SLAM Approach for Unmanned Surface Vehicle 5. ID: 1777 – Towards Benispied Localization and Mapping with Neuromorphic Computing 6. ID: 4165 – Towards Benispied Localization and Mapping with Neuromorphic Computing 6. ID: 4165 – 1979, equality Apping Host and Epidal Localization method for 20 LIDAM	Pri Mor	53.12	Industrial and Service Robotics (IND-2)	4. ID: #1006 - Automation of Coning and Deconing of trialslocks in Port Operations 5. ID: #1009 - Clon-Sec. Furkino-Powerd Solar Tracker for Invivormental Assurences 6. ID: #1009 - Clon-Sec. Furkino-Powerd Solar Tracker for Invivormental Assurences 6. ID: #1009 - Surventric Modellar and Interactive Survisiation of Virolitheras - Pattern Original Grippers 6. ID: #1009 - Surventric Modellar and Interactive Survisiation of Virolitheras - Pattern Original Grippers 6. ID: #1009 - Surventric Modellar and Interactive Survisiation of Virolitheras - Pattern Original Grippers 6. ID: #1009 - Surventric Modellar Grippers.				
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		1.10: #76 - United Safely-Awar Physical Harman-Robot Collaborative Controller 2.10: 802 - From Human to Height-Field: Predictive Shotcrefs Simulation	1										
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Fri D	ive	A1.1 Special Multi-topic Session (SMS-1)	1. IC: #93 - Probabilistic Reascent Integrating Multiple Gestures and Language Instructions 2. IC: #64 - A study on human behavior patterns in social navigation	Fri Eve	A2.1 Special Multi-topic Session (SMS-2)		1. ID: #95 - Robetic Reliators for Mobility Assistance: A Review of Recent Advances and Future Directions 2. ID: #9003 - Experimental Gast Exploration for Climbing Slopes Using a Modular Catespillar Robot				
			3. ID: #161 - Galt Phase Classification using Deep Neural Networks with Weighted Cross-Entropy Loss				3.ID: 633 - IMU-Preintegrated Radar Factors for Asynchronous Radar-LIDAR-Inertial SLAM				
			4. ID: #1 - The SLAM Coefficience Trap		í .		4. ID: #141 - Cloud4As/RoRA: an Open and Interactive Framework for UAV Simulation and Control.				
Fei D	ive	A1. 2 Special Multi-topic Session (SMS-3)	5.ID: #87 - Can LLM Agents Solve Collaborative Tasks? A Study on Ungercy-Aware Planning	Fri Dve	A2.2	Special Multi-topic Session (SMS-4)	5. ID: #30 - LegUp: Legiged Robots Assisting each Other over High Obstacles				
			6. ID: #235 - Tactille Gesture Recognition with Built-in Joint Sensors for Industrial Robots				6. ID: #118 - Force Characterization of Insect-Scale Aquatic Propulsion Based on Ruid-Structure Interaction				
			7. ID: #132 - A Gesture-Controlled Navigation System for Mobile Robots using Aprillag	Fel Dive	A2.3	Special Multi-topic Session (SMS-6)	7. ID: K24 - QueensCAMP: an RGB-D dataset for robust Visual SLAM				
Fel D	ive	A1.3 Special Multi-topic Session (SMS-5)	B. ID: 929 - Incremental Mapping with Measurement Synchronization & Compression 9. ID: 937 - Subsumption over ROS2: An implementation faithful to the Brooks theoretical proposal.		AZ.3	special Multi-copic session (sMs-e)	ID: 9221 - Path Accuracy and Repeatability Evaluation of a Lightweight and Low-Cost Parallel Delta Robot ID: 955 - End-to-End Crop Row Navisation via LIDAR-Based Deep Reinforcement Learning				
			ILP 40.7 - Subsumption over HUSLY: An implementation rational to the proposal ID. ID: 468 - Blockly-RGS Platform for Librar-Based Robotic Navisation				9. IX. 905 - LEG-CO-LING CITCH NOW INVESTIGATION HIS LILLAN-GASSED Deep Hemoricament Learning.				
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			1. ID: 476 - United Safety-Aware Physical Human-Robot Collaborative Controller 2. ID: 492 - From Human to Heinth-Field: Predictive Shotcrete Simulation	1							
			3. ID: 425 - InEXFormer: A Hybrid State Estimator for Humanoid Robots	I							
			4. ID: 474 - Hybrid Safety Verification of Multi-Agent Systems	l .							
n	of Eve	P1 POSTERS	5. ID: #170 - Overview of Educational Robotics in Latin America: A Systematic Study 6. ID: #21 - MapDeRL: Human-Inspired Indoor Exploration with Predicted Environment Contest								