

ICAR 2025 Program

DOWN TOWN									
ROOM 1									
Slot		Session Topic (Track)	Articles (ID, Affiliation, Title)		Slot		Session Topic (Track)	Articles (ID, Affiliation, Title)	
Thu-Mor	S0.1	Legged and Humanoformal Robots (LSD-1)	1. ID: 4056 - Bipedal Reachability Assessment for Humanoid Robots Using Gaze	1. ID: 4056 - Bipedal Reachability Assessment for Humanoid Robots Using Gaze	Thu-Mor	S0.1	Control, Dynamics and Manipulation (CTRL-1)	1. ID: 4057 - Development and Control of a Humanoid Robot for Navigation and Manipulation	1. ID: 4057 - Development and Control of a Humanoid Robot for Navigation and Manipulation
Thu-Mor	S0.2	Legged and Humanoformal Robots (LSD-2)	1. ID: 4057 - Humanoid Robot Navigation and Manipulation in a Dynamic Environment	1. ID: 4057 - Humanoid Robot Navigation and Manipulation in a Dynamic Environment	Thu-Mor	S0.2	Control, Dynamics and Manipulation (CTRL-2)	1. ID: 4058 - Control and Dynamics of a Humanoid Robot for Navigation and Manipulation	1. ID: 4058 - Control and Dynamics of a Humanoid Robot for Navigation and Manipulation
Thu-Mor	S0.3	Path Planning and Navigation (PNN-1)	1. ID: 4058 - Path Planning and Navigation in a Dynamic Environment	1. ID: 4058 - Path Planning and Navigation in a Dynamic Environment	Thu-Mor	S0.3	Simulation and Learning (SIM-1)	1. ID: 4059 - Simulation and Learning of a Humanoid Robot for Navigation and Manipulation	1. ID: 4059 - Simulation and Learning of a Humanoid Robot for Navigation and Manipulation
Thu-Mor	S0.4	Path Planning and Navigation (PNN-2)	1. ID: 4059 - Path Planning and Navigation in a Dynamic Environment	1. ID: 4059 - Path Planning and Navigation in a Dynamic Environment	Thu-Mor	S0.4	Simulation and Learning (SIM-2)	1. ID: 4060 - Simulation and Learning of a Humanoid Robot for Navigation and Manipulation	1. ID: 4060 - Simulation and Learning of a Humanoid Robot for Navigation and Manipulation
Thu-Mor	S0.5	Biologically Inspired Robot (BIR-1)	1. ID: 4060 - Biologically Inspired Robot for Navigation and Manipulation	1. ID: 4060 - Biologically Inspired Robot for Navigation and Manipulation	Thu-Mor	S0.5	Unmanned Aerial Vehicles (UAV-1)	1. ID: 4061 - Unmanned Aerial Vehicle for Navigation and Manipulation	1. ID: 4061 - Unmanned Aerial Vehicle for Navigation and Manipulation
Thu-Mor	S0.6	Path Planning and Navigation (PNN-3)	1. ID: 4061 - Path Planning and Navigation in a Dynamic Environment	1. ID: 4061 - Path Planning and Navigation in a Dynamic Environment	Thu-Mor	S0.6	Control, Dynamics and Manipulation (CTRL-3)	1. ID: 4062 - Control and Dynamics of a Humanoid Robot for Navigation and Manipulation	1. ID: 4062 - Control and Dynamics of a Humanoid Robot for Navigation and Manipulation
Thu-Mor	S0.7	Path Planning and Navigation (PNN-4)	1. ID: 4062 - Path Planning and Navigation in a Dynamic Environment	1. ID: 4062 - Path Planning and Navigation in a Dynamic Environment	Thu-Mor	S0.7	Control, Dynamics and Manipulation (CTRL-4)	1. ID: 4063 - Control and Dynamics of a Humanoid Robot for Navigation and Manipulation	1. ID: 4063 - Control and Dynamics of a Humanoid Robot for Navigation and Manipulation
Thu-Mor	S0.8	Robotics Vision and Perception (RVP-1)	1. ID: 4063 - Robotics Vision and Perception in a Dynamic Environment	1. ID: 4063 - Robotics Vision and Perception in a Dynamic Environment	Thu-Mor	S0.8	Unmanned Aerial Vehicles (UAV-2)	1. ID: 4064 - Unmanned Aerial Vehicle for Navigation and Manipulation	1. ID: 4064 - Unmanned Aerial Vehicle for Navigation and Manipulation
Thu-Mor	S0.9	Robotics Vision and Perception (RVP-2)	1. ID: 4064 - Robotics Vision and Perception in a Dynamic Environment	1. ID: 4064 - Robotics Vision and Perception in a Dynamic Environment	Thu-Mor	S0.9	Unmanned Aerial Vehicles (UAV-3)	1. ID: 4065 - Unmanned Aerial Vehicle for Navigation and Manipulation	1. ID: 4065 - Unmanned Aerial Vehicle for Navigation and Manipulation
Fri-Mor	S1.0	Legged and Humanoformal Robots (LSD-3)	1. ID: 4065 - Legged and Humanoformal Robots for Navigation and Manipulation	1. ID: 4065 - Legged and Humanoformal Robots for Navigation and Manipulation	Fri-Mor	S1.0	Unmanned Aerial Vehicles (UAV-4)	1. ID: 4066 - Unmanned Aerial Vehicle for Navigation and Manipulation	1. ID: 4066 - Unmanned Aerial Vehicle for Navigation and Manipulation
Fri-Mor	S1.1	Robotics Vision and Perception (RVP-3)	1. ID: 4066 - Robotics Vision and Perception in a Dynamic Environment	1. ID: 4066 - Robotics Vision and Perception in a Dynamic Environment	Fri-Mor	S1.1	Industrial and Service Robotics (ISR-1)	1. ID: 4067 - Industrial and Service Robotics for Navigation and Manipulation	1. ID: 4067 - Industrial and Service Robotics for Navigation and Manipulation
Fri-Mor	S1.2	Robotics Vision and Perception (RVP-4)	1. ID: 4067 - Robotics Vision and Perception in a Dynamic Environment	1. ID: 4067 - Robotics Vision and Perception in a Dynamic Environment	Fri-Mor	S1.2	Industrial and Service Robotics (ISR-2)	1. ID: 4068 - Industrial and Service Robotics for Navigation and Manipulation	1. ID: 4068 - Industrial and Service Robotics for Navigation and Manipulation

ROOM 1 MAIN HALL		
Thu-Mor	P1	POSTERS

ANCHIPURAC									
ROOM 1					ROOM 2				
A0.1					A0.1				
A0.2					A0.2				
A0.3					A0.3				
A0.4					A0.4				

ANCHIPURAC MAIN HALL		
Thu-Mor	P1	POSTERS